Naive Bayes Text Classification

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Outline

Basic Probability and Notation Bayes Law and Naive Bayes Classification Smoothing Class Prior Probabilities Naive Bayes Classification Summary

Crash Course in Basic Probability

Discrete Random Variable

- A is a discrete random variable if:
 - A describes an event with a finite number of possible outcomes (discrete vs continuous)
 - A describes and event whose outcomes have some degree of uncertainty (random vs. pre-determined)

Discrete Random Variables Examples

- A = the outcome of a coin-flip
 - outcomes: heads, tails
- A = it will rain tomorrow
 - outcomes: rain, no rain
- A = you have the flu
 - outcomes: flu, no flu
- A = your final grade in this class
 - outcomes: F, L, P, H

Discrete Random Variables Examples

- A = the color of a ball pulled out from this bag
 - outcomes: **RED**, **BLUE**, **ORANGE**



Probabilities

- Let P(A=X) denote the probability that the outcome of event A equals X
- For simplicity, we often express P(A=X) as P(X)
- Ex: P(RAIN), P(NO RAIN), P(FLU), P(NO FLU), ...

Probability Distribution

- A probability distribution gives the probability of each possible outcome of a random variable
- P(RED) = probability of pulling out a red ball
- P(BLUE) = probability of pulling out a blue ball
- P(ORANGE) = probability of pulling out an orange ball



Probability Distribution

- For it to be a probability distribution, two conditions must be satisfied:
 - the probability assigned to each possible outcome must be between 0 and 1 (inclusive)
 - the <u>sum</u> of probabilities assigned to all outcomes must equal 1

 $0 \le P(RED) \le I$ $0 \le P(BLUE) \le I$ $0 \le P(ORANGE) \le I$ P(RED) + P(BLUE) + P(ORANGE) = I

Probability Distribution Estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- **P(RED)** = ?
- **P(BLUE)** = ?
- **P(ORANGE)** = ?



Probability Distribution estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- P(RED) = 10/20 = 0.5
- P(BLUE) = 5/20 = 0.25
- P(ORANGE) = 5/20 = 0.25
- P(RED) + P(BLUE) + P(ORANGE) = 1.0



Probability Distribution assigning probabilities to outcomes

- Given a probability distribution, we can assign probabilities to different outcomes
- I reach into the bag and pull out an orange ball. What is the probability of that happening?
- I reach into the bag and pull out two balls: one red, one blue.
 What is the probability of that happening?
- What about three orange balls?



What can we do with a probability distribution?

- If we assume that each outcome is independent of previous outcomes, then the probability of a <u>sequence</u> of outcomes is calculated by <u>multiplying</u> the individual probabilities
- Note: we're assuming that when you take out a ball, you put it back in the bag before taking another



What can we do with a probability distribution?

P() = ??



What can we do with a probability distribution?

- $P(\bigcirc) = 0.25$
- P(**(**) = 0.5
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-----) = 0.25 \times 0.50 \times 0.25$
- $P(\bigcirc \bigcirc \bigcirc \bigcirc) = 0.25 \times 0.50 \times 0.25 \times 0.50$



Conditional Probability

- P(A,B): the probability that event A and event B both occur
- P(A|B): the probability of event A occurring given prior knowledge that event B occurred

Conditional Probability

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



- ▲
 P(● | ▲) = ??
- $P(\bigcirc | A) = ??$



- • P(● | B) = ??
- P(-|B) = ??

Conditional Probability

P(RED) = 0.50P(BLUE) = 0.25**P(ORANGE)** = 0.25 Α (A) = 0.25• P(• P(P((|A| = 0.50• P(• P((|A| = 0.016**P(** •

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50



B P(| B) = 0.00

- P(- | B) = 0.25
 - | B) = 0.00

Chain Rule

- $P(A, B) = P(A|B) \times P(B)$
- Example:
 - probability that it will rain today (B) <u>and</u> tomorrow (A)
 - probability that it will rain today (B)
 - probability that it will rain tomorrow (A) given that it will rain today (B)

- $P(A, B) = P(A|B) \times P(B) = P(A) \times P(B)$
- Example:
 - probability that it will rain today (**B**) <u>and</u> tomorrow (**A**)
 - probability that it will rain today (B)
 - probability that it will rain tomorrow (A) given that it will rain today (B)
 - probability that it will rain tomorrow (A)



A



B

 $\mathsf{P}(\bigcirc | \mathsf{A}) ?= \mathsf{P}(\bigcirc)$



A



B

 $P(\bigcirc | A) > P(\bigcirc)$



A



B

 $P(\bigcirc | A) ?= P(\bigcirc)$



A



B

$\mathsf{P}(\bigcirc | \mathsf{A}) = \mathsf{P}(\bigcirc)$

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Bayes' Law



Bayes' Law

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Derivation of Bayes' Law

P(A,B) = P(A,B)

Always true!

 $P(A|B) \times P(B) = P(B|A) \times (B)$ Chain Rule!

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Divide both sides by P(B)!

Bayes Rule
$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Confidence of POS prediction given instance D

$$P(POS|D) = \frac{P(D|POS) \times P(POS)}{P(D)}$$

Confidence of NEG prediction given instance D

$$P(NEG|D) = \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

• Given instance D, predict positive (POS) if:

$P(POS|D) \ge P(NEG|D)$

• Given instance D, predict positive (POS) if:

$$\frac{P(D|POS) \times P(POS)}{P(D)} \ge \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

• Given instance D, predict positive (POS) if:



• Given instance D, predict positive (POS) if:

 $P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Our next goal is to estimate these parameters from the training data!



P(D|NEG) = ??
 P(D|POS) = ??

- Our next goal is to estimate these parameters from the training data!
- **P(NEG)** = % of training set documents that are **NEG**
- **P(POS)** = % of training set documents that are **POS**
- **P(D|NEG)** = ??
- **P(D|POS)** = ??

Remember Conditional Probability?

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



- $P(\bigcirc |A) = 0.25$
- P(-|A) = 0.50
- P(| A) = 0.25

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50



• $P(\bigcirc | B) = 0.00$

 $| \mathbf{B} | = 0.50$ P(

• P(-|B) = 0.50



P(D|POS) = ?? P(D|NEG) = ??

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
I	0	I	0	Ι	0	0	Ι	•••	0	positive
0	Ι	0	Ι	Ι	0	Ι	-	•••	0	positive
0	I	0	Ι	Ι	0	I	0	•••	0	positive
0	0	I	0	Ι	Ι	0	Ι	•••	Ι	positive
:						:		•••		
Ι	Ι	0	Ι	Ι	0	0	I		I	positive

• We have a problem! What is it?



- We have a problem! What is it?
- Assuming n binary features, the number of possible combinations is 2ⁿ
- $2^{1000} = 1.071509e+301$
- And in order to estimate the probability of each combination, we would require multiple occurrences of each combination in the training data!
- We could never have enough training data to reliably estimate P(D|NEG) or P(D|POS)!

- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- In other words, the value of a particular feature is only dependent on the class value

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8	 w_n	sentiment
I	0	I	0	Ι	0	0	Ι	 0	positive
0	Ι	0	Ι	Ι	0	Ι	Ι	 0	positive
0	Ι	0	Ι	Ι	0	Ι	0	 0	positive
0	0	I	0	I	I	0	I	 I	positive
:	:	:	:	:	:	:	:	 :	:
Ι	I	0	I	I	0	0	I	 I	positive

- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- Example: we have <u>seven</u> features and **D** = **IOIIOII**
- P(|0||0||POS) =

 $P(w_1 = |POS) \times P(w_2 = 0|POS) \times P(w_3 = |POS) \times P(w_4 = |POS) \times P(w_5 = 0|POS) \times P(w_6 = |POS) \times P(w_7 = |POS)$

• P(|0||0|||NEG) =

 $P(w_1=||NEG) \times P(w_2=0|NEG) \times P(w_3=||NEG) \times P(w_4=||NEG) \times P(w_5=0|NEG) \times P(w_6=||NEG) \times P(w_7=||NEG))$

• Question: How do we estimate P(w₁=|POS) ?

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
Ι	0	I	0	Ι	0	0	Ι	•••	0	positive
0	I	0	Ι	Ι	0	Ι	Ι	•••	0	negative
0	I	0	Ι	Ι	0	-	0	•••	0	negative
0	0	I	0	Ι	Ι	0	Ι	•••	Ι	positive
:	÷									
Ι	I	0	Ι	Ι	0	0	Ι		Ι	negative

• Question: How do we estimate P(w₁= |POS) ?



 $P(w_1 = | | POS) = ??$

• Question: How do we estimate P(w₁=|POS)?



 $P(w_1 = || POS) = a / (a + c)$

• Question: How do we estimate P(w₁=1/0|POS/NEG) ?



 $P(w_1=|POS) = a / (a + c)$ $P(w_1=0|POS) = ??$ $P(w_1=|NEG) = ??$ $P(w_1=0|NEG) = ??$

• Question: How do we estimate P(w₁=1/0|POS/NEG) ?



 $P(w_{1}=1|POS) = a / (a + c)$ $P(w_{1}=0|POS) = c / (a + c)$ $P(w_{1}=1|NEG) = b / (b + d)$ $P(w_{1}=0|NEG) = d / (b + d)$

• Question: How do we estimate P(w₂=1/0|POS/NEG)?



 $P(w_{2}=I|POS) = a / (a + c)$ $P(w_{2}=0|POS) = c / (a + c)$ $P(w_{2}=I|NEG) = b / (b + d)$ $P(w_{2}=0|NEG) = d / (b + d)$

 The value of a, b, c, and d would be different for different features w₁, w₂, w₃, w₄, w₅,, w_n

• Given instance **D**, predict positive (**POS**) if:

 $P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Given instance D, predict positive (POS) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

• Given instance **D** = **IOIIOII**, predict positive (**POS**) if:

 $P(w_1 = | POS) \times P(w_2 = 0 | POS) \times P(w_3 = | POS) \times P(w_4 = | POS) \times P(w_5 = 0 | POS) \times P(w_6 = | POS) \times P(w_7 = | POS) \times P(POS) \times P(POS)$

>

 $P(w_1 = ||NEG) \times P(w_2 = 0|NEG) \times P(w_3 = ||NEG) \times P(w_4 = ||NEG) \times P(w_5 = 0|NEG) \times P(w_6 = ||NEG) \times P(w_7 = ||NEG) \times P(NEG)$

• We still have a problem! What is it?

• Given instance **D** = **IOIIOII**, predict positive (**POS**) if:

 $\begin{array}{l} \mathsf{P}(w_1 = \| | \mathsf{POS}) \times \mathsf{P}(w_2 = \mathbf{0} | \mathsf{POS}) \times \mathsf{P}(w_3 = \| | \mathsf{POS}) \times \mathsf{P}(w_4 = \| | \\ \mathsf{POS}) \times \mathsf{P}(w_5 = \mathbf{0} | \mathsf{POS}) \times \mathsf{P}(w_6 = \| | \mathsf{POS}) \times \mathsf{P}(w_7 = \| | \mathsf{POS}) \times \mathsf{P}(\mathsf{POS}) \\ \mathsf{P}(\mathsf{POS}) \end{array}$

 $\begin{array}{l} \mathsf{P}(\mathsf{w}_1 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_2 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_3 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_4 = {\color{black}{|}} {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_5 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_7 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6 = {\color{black}{|}} \mathsf{NEG}) \times \mathsf{P}(\mathsf{w}_6$

• Otherwise, predict negative (**NEG**)

What if this never happens in the training data?

Smoothing Probability Estimates

- When estimating probabilities, we tend to ...
 - Over-estimate the probability of observed outcomes
 - Under-estimate the probability of unobserved outcomes
- The goal of smoothing is to ...
 - Decrease the probability of observed outcomes
 - Increase the probability of unobserved outcomes
- It's usually a good idea
- You probably already know this concept!

Smoothing Probability Estimates

- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.







Smoothing Probability Estimates

- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.
- MOUNTAIN LION: You should have learned about smoothing by taking INLS 613. Yum!





Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG) ?



 $P(w_{2}=I|POS) = a / (a + c)$ $P(w_{2}=0|POS) = c / (a + c)$ $P(w_{2}=I|NEG) = b / (b + d)$ $P(w_{2}=0|NEG) = d / (b + d)$

Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG) ?

	POS	NEG		
w ₂ =	a + 1	b + 1		
w ₂ = 0	c + 1	d + 1		

 $P(w_2 = | | POS) = ??$

 $P(w_2=0|POS) = ??$

P(w₂=||NEG) = ??

P(w₂=0|NEG) = ??

Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG)?

	POS	NEG		
w ₂ =	a + 1	b + I		
w ₂ = 0	c + 1	d + 1		

 $P(w_{2}=I|POS) = (a + I) / (a + c + 2)$ $P(w_{2}=0|POS) = (c + I) / (a + c + 2)$ $P(w_{2}=I|NEG) = (b + I) / (b + d + 2)$

 $P(w_2=0|NEG) = (d + I) / (b + d + 2)$

• Given instance D, predict positive (POS) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

Naive Bayes Classification

- Naive Bayes Classifiers are simple, effective, robust, and very popular
- Assumes that feature values are conditionally independent given the target class value
- This assumption does not hold in natural language
- Even so, NB classifiers are very powerful
- Smoothing is necessary in order to avoid zero probabilities